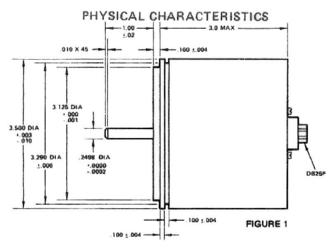


ENCODER DATA SHEET

INC35 & BIC35 INCREMENTAL ENCODERS

FEATURES

- Optical incremental encoder with long life LED light source
- INC35 is intended for rotation in one direction.
- BIC35 is intended for bidirectional rotation.
- Standard models with or without an index pulse
- BIC35 models output square waves in quadrature, or optionally pulse trains
- Several choices of output line drivers are optional.
- Standard units operate from +5 VDC. Other supply voltage ranges are optional.
- Internal count multiplication and direction sensing logic.
- Shaft seal, alternate output connector, low torque bearings are optional.
- Extended temperature range optional.



APPLICATIONS

- Radar Antennas
- Calibration, Test, and Other Ground Support Equipment
- Automatic Weight Logging
- Liquid Level Measurements

USE THIS BLOCK DIAGRAM TO ORDER

CODE FORMAT:

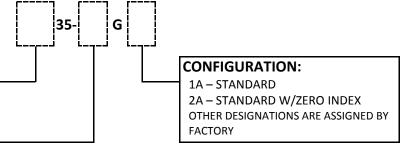
INC – UNIDIRECTIONAL INCREMENTAL BIC – BIDIRECTIONAL INCREMENTAL

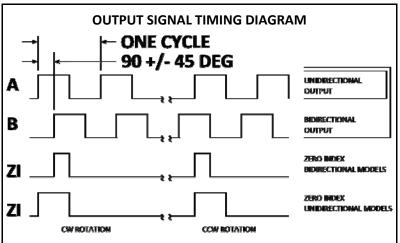
CYCLES PER 360°:

UP TO 5000 -

USE DESIGNATION FROM TABLE 1

TABLE 1			
CYCLES PER 360°	DESIGNATION		
1024	10		
1800	182		
2048	11		
3600	362		
4096	12		
5000	502		





Approved for general release.

Page 2 Encoder Data Sheet

MECHANICAL CHARACTERISTICS		ELECTRICAL CHARACTERISTICS	
Dimensions	per Figure 1	■ Code Format	Optional – Unidirectional or Bidirectional with or without Zero Index
■ Weight	48.0 oz maximum	■ Input Power	5.0 VDC ± 5% @ 225 mA
■ Starting Torque @ 25°C	0.5 oz-in maximum	Output Circuitry	DTL-TTL compatible. Fan out: 10 unit loads (UL) (1 UL = 1 DTL gate)
Moment of Inertia	0.6 oz-in² maximum	Output Logic Levels	
		► Logic '1'	Vcc with 1K ±10% ohm source impedance.
		► Logic '0'	0.0 to 0.5 VDC max with
			12 mA sink current max
Slewing Speed	3000 RPM maximum	Illumination Source	
(See note 1)		► Type	Solid State (GaAs)
		Useful Life	100,000 Hrs min.
Operating Speed (See Note 1)		ENVIRONMENTAL	
Models without Zero	(50KHz)	Temperature	
index	$= \left(\frac{50KHz}{cycles/360^{\circ}}\right) \times 60$	Operating	0°C to 71°C
	(cycles / 300)	▶ Storage	-40°C to 85°C
Models with Zero index	$= \left(\frac{15KHz}{cycles/360^{\circ}}\right) \times 60$	Vibration	5 to 500 Hz @ 20 g's
		■ Shock	30 g's for 11 ms duration
Shaft rotation	Continuous & Reversible		
Mechanical Life	10 ⁹ Revolutions min		
■ Shaft loading	5.0 lbs max		

NOTES:

- 1 Slewing Speed is the maximum mechanical speed to which the coder may be subjected without permanent degradation of performance. Operating Speed is the maximum mechanical speed at which the encoder may be read while maintaining full accuracy. In cases where Operating Speed calculates to higher value than Slewing Speed, the latter is the limiting factor. Higher operating Speeds up to 150 kHz are permissible, particularly with one channel models where quadrature alignment is not a applicable, and with two channel models where a broader quadrature quadrature alignment tolerance is permitted. quadrature tolerance specified (+45 Elect Deg) is Worst Case and considers maximum operating speed, input voltage tolerance and full temperature range.
- 2 Other input voltages (up to 15 volts) can be facilitated; Logical '1' level will be equal to VCC with a 1K ±10% ohm source impedance. Additionally, higher sink currents (up to 45 mA) can be facilitated; Logical '0' level will be 1 volt typical and 1.75 volt maximum when sinking 45 mA. Specify input voltage (Vcc) and tolerance, and sink current requirement on purchase order (if other than standard).
- 3 Special configurations, such as the following, are available on special order:
 - Low Torque Bearings
 - Line Driver Output Circuitry
 - Internal Count Multiplication and Direction Sensing Logic
 - Other Resolutions
 - Shaft Seals
 - Extended Operating Temperature Range

Specifications Subject to Change Without Notice

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